

Applications of Formal Verification Formal Software Design: Modelling in Event-B

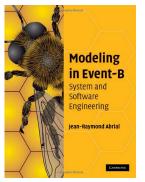
Dr. Vladimir Klebanov · Dr. Mattias Ulbrich | SS 2015

KIT – INSTITUT FÜR THEORETISCHE INFORMATIK



Literatur





Jean-Raymond Abrial: **Modelling in Event-B** System and Software Enginieering Cambridge University Press, 2010

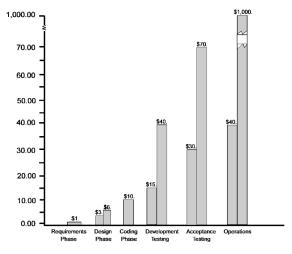


Jean-Raymond Abrial: **The B-Book: Assigning programs to meanings** Cambridge University Press, 1996

Abstraction and Refinement – Introduction

Late fault recovery is expensive



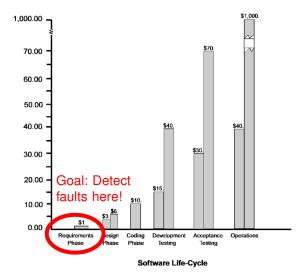


Software Life-Cycle

["Extra Time Saves Money", W. Knuffel, Computer Language, 1990]

Late fault recovery is expensive





["Extra Time Saves Money", W. Knuffel, Computer Language, 1990]



- Systems are inherently complex
- Unconsidered situations, corner cases
- Ambiguous natural language requirements
- Component interplay



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The only tool to **master complexity** is **abstraction**.

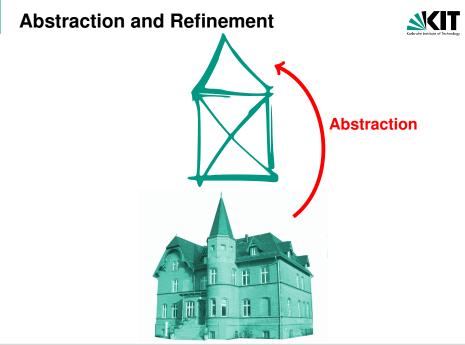
CLIFF JONES

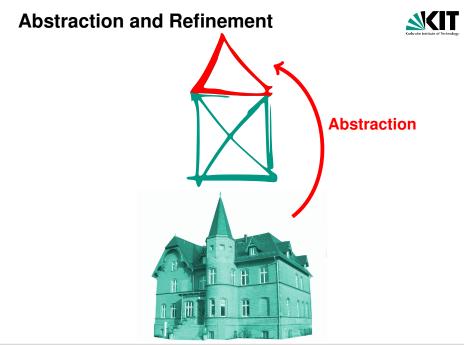
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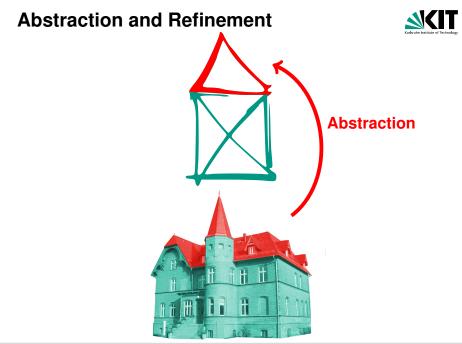
Abstraction and Refinement

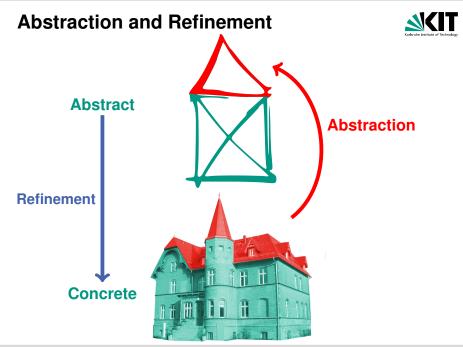












Abstraction



Abstraction

- reduce system complexity
- without removing important properties
- make the model susceptible to formal analysis

and the inverse

Refinement

- enrich abstract model with details
- introduce a new particular aspect
- iterative process: add complexity in a stepwise fashion

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Abstraction in Engineering



Abstraction is an important tool in engineering

Established means of abstraction

- Mechanical engineering: BLUEPRINTS
- Electrical engineering: DATASHEETS
- CIRCUIT DIAGRAMS
- Architecture: FLOOR PLANS

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Abstract descriptions remove unnecessary details, concentrate on one aspect



Extracts from datasheet for an IC with four NAND gates



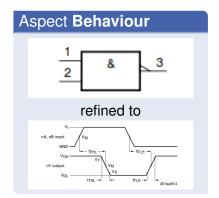
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Aspect Behaviour





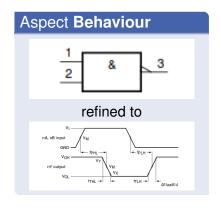
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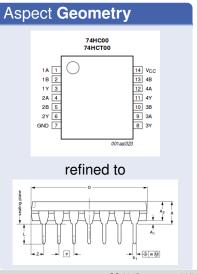


Aspect Geometry



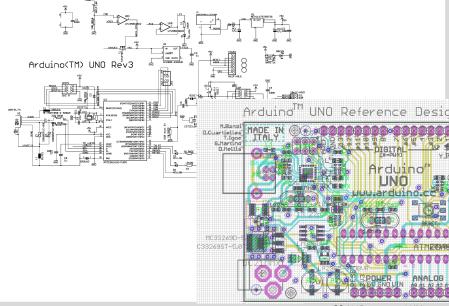
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Schematic Diagram vs. PCB Layout





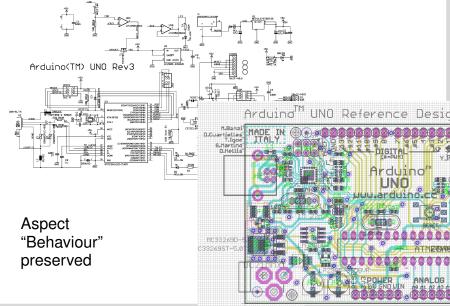
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Schematic Diagram vs. PCB Layout





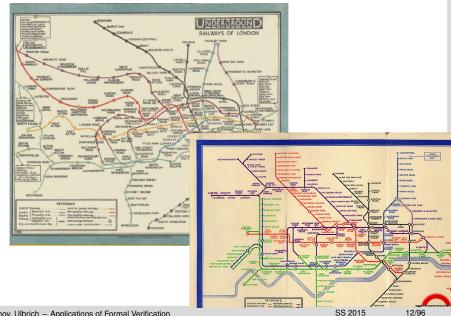
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Beck diagrams (1931)

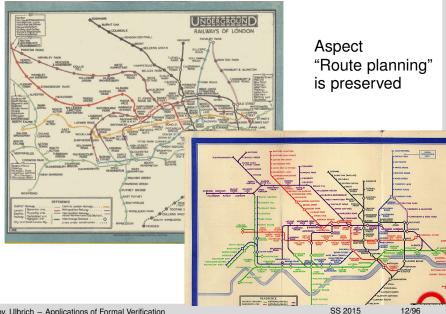




Klebanov, Ulbrich - Applications of Formal Verification

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Property preservation



Abstraction with focus on particular aspect

System properties w.r.t. that aspect must also hold in the abstraction.

Refinement with focus on particular aspect

Properties of abstract model w.r.t. that aspect must be inherited by the refined model.

Examples:

- Abstraction: "The shortest tube travel from Liverpool St. to Westminster has 8 stops and 2 changes."
- Refinement: Abstract: Input "a = 1" gives output "b = 1"
 Concrete: High voltage on pin A gives high voltage on pin B

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Properties of abstract model w.r.t. that aspect must be inherited by the refined model. That's what we will formally prove

in the next sections.

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Two areas of abstraction and refinement in formal methods:

Conceptual abstraction



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- reduce complexity for more comprehensibility
- focus on a particular system aspect
- provided by designer/developer
- refinement introduces new aspect



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- abstract from given predicates to uninterpreted predicates
- computed automatically
- refinement driven by failed proofs (Counter-Example Guided Abstraction Refinement, CEGAR)



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That's what we will look into in the next sections.

- reduce complexity to enhance performance/reach of a tool
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Event-B – Introduction

Event-B



- EventB is a formalism for modelling and reasoning about discrete systems.
 - for their structure (how can their state be described) and
 - for their behaviour (how can the evolution of their state be described)
- Models are formulated using set theory
- Event-based evolution of the original **B** Method

Tool-support:

- RODIN deductive verification, theorem prover: proofs
- Pro-B model checking, animator: counterexamples

Central Concepts



Variables and Events

- *Variables* model the current state within the state space.
- Events describe operations to model the system behaviour

Invariants

- properties to be maintained by system
- formal proof obligations to show that

Refinement

- Behaviour of refining model is compatible with abstract model
- formal proof obligation to show that
- Hence, invariants of abstract model are inherited by concrete model

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Event-B models

systems state evolution over time, triggered by events

Event-B models consist of contexts and machines:

Contexts

Static, rigid, constant parts that do not change over time.

Machines

Dynamic, volatile, evolving parts that do change over time.



Event-B models consist of contexts and machines:

Contexts

- Carrier sets (ground types, universes, "urelements")
- Constants (state-independent symbols, rigid symbols)
- Axioms (formulas valid by stipulation)
- Theorems (formulas proved valid)

Machines

- Context references (which symbols are available)
- Variables (state-dependent symbols, non-rigid symbols, program variables)
- Invariants (formulas true in every reachable system state)
- Events (state transition descriptions)



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Students and Exams – Requirements

- R1 Every **student** must take a final exam in a **subject** of their choice.
- R2 They can have **attempts** without yet failing or passing.
- R3 Eventually they can **pass** or **fail**, but **never both**.



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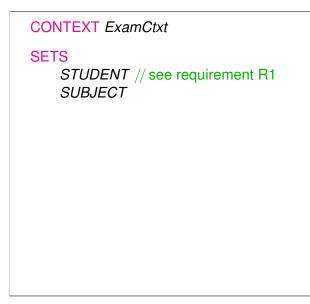


CONTEXT ExamCtxt

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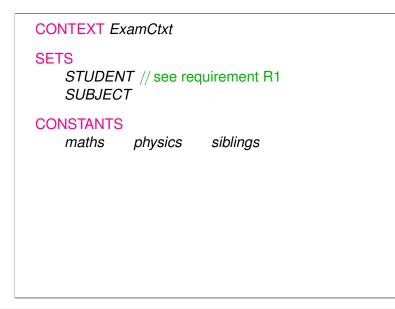




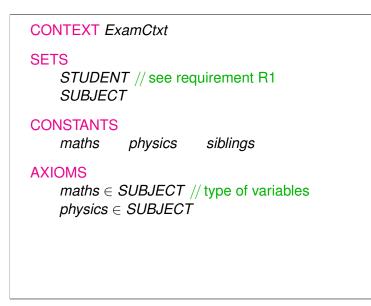




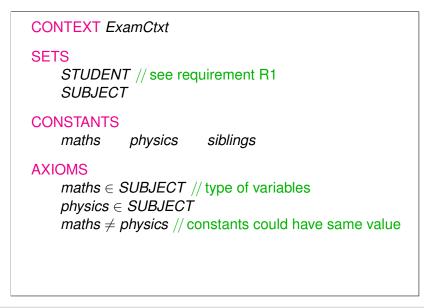




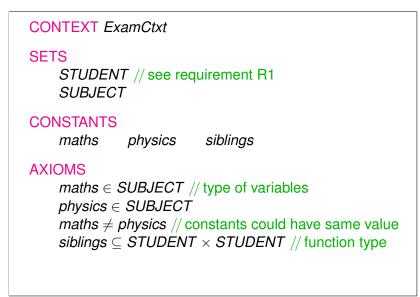














```
CONTEXT ExamCtxt
SETS
    STUDENT // see requirement R1
    SUBJECT
CONSTANTS
             physics
    maths
                            siblings
AXIOMS
    maths \in SUBJECT // type of variables
    physics ∈ SUBJECT
    maths \neq physics // constants could have same value
    siblings \subset STUDENT \times STUDENT // function type
    \forall s \cdot s \in STUDENT \Rightarrow (s \mapsto s) \notin siblings // irreflexive
     // . . .
```



MACHINE ExamAbstract



MACHINE ExamAbstract SEES ExamCtxt

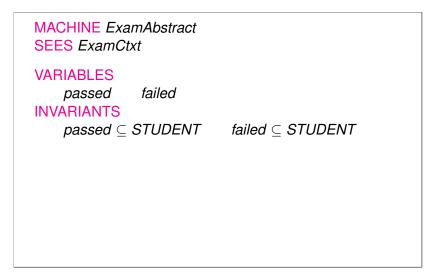


MACHINE ExamAbstract SEES ExamCtxt

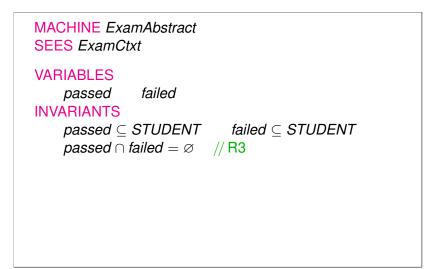
VARIABLES

passed failed

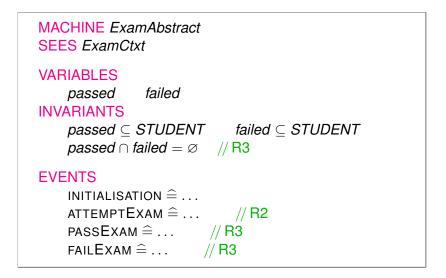












Exam Machine (2)



MACHINE ExamAbstract VARIABLES passed failed

EVENTS INITIALISATION $\widehat{=}$ failed := \emptyset passed := \emptyset

Exam Machine (2)



```
MACHINE ExamAbstract
VARIABLES passed failed ....
EVENTS
INITIALISATION \hat{=}
     failed := \emptyset
    passed := \emptyset
PASSEXAM ≘
  ANY s grade
  WHERE s \in STUDENT \land grade \leq 4
  THEN passed := passed \cup \{s\}
```

Exam Machine (2)



```
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FAII EXAM ≘
  ANY s grade
  WHERE s \in STUDENT \land grade > 4
  THEN failed := failed \cup {s}
```

Invariant violated



```
MACHINE ExamAbstract
VARIABLES passed failed
INVARIANTS passed \cap failed = \varnothing ...
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```

Invariant violated



```
MACHINE ExamAbstract
VARIABLES passed failed
INVARIANTS passed \cap failed = \varnothing ...
EVENTS
PASSEXAM ≘
  ANY s grade
  WHERE s \in STUDENT \setminus (failed \cup passed) \land grade \leq 4
  THEN passed := passed \cup \{s\}
FAII EXAM ≘
  ANY s grade
  WHERE s \in STUDENT \setminus (failed \cup passed) \land grade > 4
  THEN failed := failed \cup {s}
```

Underspecified model



```
EVENTS
PASSEXAM ≘
  ANY s grade WHERE grade \leq 4 \land s \in \ldots
  THEN passed := passed \cup \{s\}
FAIL EXAM ≘
  ANY s grade WHERE grade > 4 \land s \in ...
  THEN failed := failed \cup {s}
ATTEMPTEXAM ≘
  ANY s grade WHERE grade \in \mathbb{N} \land s \in ...
  THEN skip
```

Underspecified model

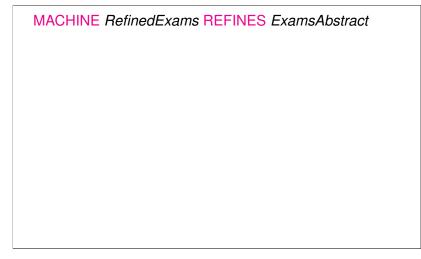


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Additional requirement

R4 Any student may attempt the exam three times and ultimately fails if the fourth attempt is unsuccessful.







MACHINE RefinedExams REFINES ExamsAbstract VARIABLES passed attempts



```
MACHINE RefinedExams REFINES ExamsAbstract
VARIABLES passed attempts
INVARIANTS
    attempts \in STUDENT \rightarrow \mathbb{N} // typing for attempts
    failed = {s \cdot attempts(s) = 4} // coupling invariant
```



```
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VARIABLES passed attempts
INVARIANTS
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EVENTS
INITIAL ISATION \cong REFINES INITIAL ISATION
    passed := \emptyset
    attempts := {s \cdot s \in STUDENT \mid (s \mapsto 0)}
```



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VARIABLES passed attempts
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EVENTS
INITIAL ISATION \cong REFINES INITIAL ISATION
    passed := \emptyset
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EXAMULTIMATE FAIL \cong REFINES EXAMEAL
EXAMMISSED \cong REFINES EXAMATTEMPT...
EXAMPASSED \cong REFINES EXAMPASSED
```



```
EVENTS
EXAMULTIMATE FAIL \hat{=} REFINES EXAMEAL
  ANY s grade
  WHERE ... \land grade > 4 \land attempts(s) = 3
  THEN
    attempts(s) := attempts(s) + 1
FXAMMISSED \cong BEFINES FXAMATTEMPT
  ANY s grade
  WHERE ... \land grade > 4 \land attempts(s) < 3
  THFN
    attempts(s) := attempts(s) + 1
. . .
```



This refinment takes now also R4 into account.

Refinement preserves invariants

- ! Every possible event of *RefinedExams* is a possible event in *ExamsAbstract*
- ⇒ Every invariant of *ExamsAbstract* is also an invariant of *RefinedExams*

We will come back to this more formally ...

Set Theory – Equipment for formal modelling

Set theory – a universal modelling language



Not only used in Event-B.

Set theory also used for modelling in ...

- Z
- Object-Z, Z++
- (classical) B
- Event-B
- Alloy
- • •



Formal language in Event-B models

Typed First Order Set Theory with Additional Theories

Every term in Event-B has a unqiue type.

Types are *part of the syntax* of Event-B and some expressions are syntactically forbidden:

maths \in *failed* is syntactially invalid.

(remember: $math \in SUBJECT$, $failed \subseteq STUDENT$)

"You can't compare apples and oranges."



Formal language in Event-B models

- sets are objects in the logic
- first order axioms define the semantics of sets
- quantification over sets is allowed
- quantification over predicates, functions is not allowed
- (Foundation is a typed Zermelo-Fraenkel axiomatisation)



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Formal language in Event-B models

Typed First Order Set Theory with Additional Theories

There are additional theories with fixed semantics

- integers
- more theories (datatypes) can be added by user (an extension to the system)



1 BOOL and \mathbb{Z} are types

- ② Every carrier set declared in a CONTEXT is a type.
- If *T* is a type then ℙ(*T*) is a type. Semantics: ℙ(*T*) is the set of all subsets of *T* (powerset).
- **4** If T_1, T_2 are types then $T_1 \times T_2$ is a type. *Semantics:* $T_1 \times T_2$ is the set of all ordered pairs (a, b) with $a \in T_1$ and $b \in T_2$ (Cartesian produt).



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Assume that the expression $\{s \mid \phi\}$ for any formula ϕ denotes a set. Let $R := \{s \mid s \notin s\}$. Not allowed with types. One observes: $R \in R \iff R \notin R \notin$ (*This crushed naive set theory in early 1900s.*)

Sets



Constructors for sets:

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Sets



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- set comprehension $\{x \cdot \varphi \mid e\}$ formula φ , term e : T, result of type $\mathbb{P}(T)$ example: $\{x \cdot x \ge 2 \mid x * x\} = \{4, 9, 16, \ldots\}$



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Kinds of relations



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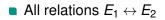






dom ran





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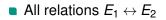


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• All total relations $E_1 \leftrightarrow E_2$ $(\operatorname{dom}(R) = E_1)$







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ran

dom

dom ran

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All total surjections E₁ «» E₂

Functional relations

Observation



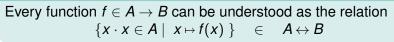
Every function $f \in A \to B$ can be understood as the relation $\{x \cdot x \in A \mid x \mapsto f(x)\} \in A \leftrightarrow B$

• Partial functions $E_1 \rightarrow E_2 \subseteq E_1 \leftrightarrow E_2$ $(\forall x, y, z \cdot x \mapsto y \in R \land x \mapsto z \in R \Rightarrow y = z) (*)$



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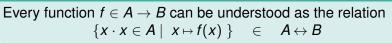
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dom ran





Intersection of relation classes give new classes:

- Total injections $E_1 \rightarrow E_2 = (E_1 \rightarrow E_2) \cap (E_1 \rightarrow E_2)$
- Partial surjections $E_1 \twoheadrightarrow E_2 = (E_1 \leftrightarrow E_2) \cap (E_1 \leftrightarrow E_2)$
- Total surjections $E_1 \twoheadrightarrow E_2 = (E_1 \to E_2) \cap (E_1 \twoheadrightarrow E_2)$
- Bijections $E_1 \rightarrowtail E_2 = (E_1 \twoheadrightarrow E_2) \cap (E_1 \rightarrowtail E_2)$

Example: File system



CONTEXT FileSystemCtx

Example: File system



CONTEXT FileSystemCtx SETS OBJECT



 $\begin{array}{l} \textbf{CONTEXT} \ \textit{FileSystemCtx} \\ \textbf{SETS} \ \textit{OBJECT} \\ \textbf{CONSTANTS} \ \textit{files}, \textit{dirs}, \textit{root} \\ \textbf{AXIOMS} \ \textit{files} \subseteq \textit{OBJECT}, \textit{dirs} \subseteq \textit{OBJECT}, \\ \textit{root} \in \textit{dirs}, \textit{files} \cap \textit{dirs} = \varnothing \end{array}$



CONTEXT FileSystemCtx SETS OBJECT CONSTANTS files, dirs, root AXIOMS files \subseteq OBJECT, dirs \subseteq OBJECT, root \in dirs, files \cap dirs $= \varnothing$

MACHINE FileSystem SEES FileSystemCtx VARIABLES tree, parent



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CONTEXT FileSystemCtx
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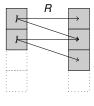


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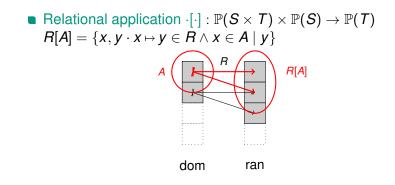


• Relational application $\cdot [\cdot] : \mathbb{P}(S \times T) \times \mathbb{P}(S) \to \mathbb{P}(T)$ $R[A] = \{x, y \cdot x \mapsto y \in R \land x \in A \mid y\}$





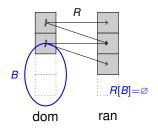




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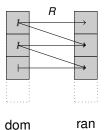
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Problem: What if $f[\{e\}]$ is not a one-element set? Solution: Well-definedness needs to be proved (1) $f \in S \leftrightarrow T$ (not an arbitrary relation in $S \leftrightarrow T$) (2) $e \in \text{dom}(f)$ everytime a functional application is used.

Concept

Limit the domain or range of a relation to a subset.



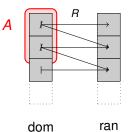
Klebanov, Ulbrich – Applications of Formal Verification





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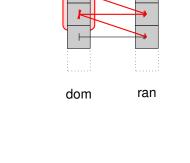
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Α

R

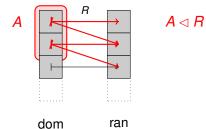
 $A \triangleleft R$





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$$A \lhd R := \{x, y \cdot x \mapsto y \in R \land x \in A \mid x \mapsto y\} \subseteq R$$

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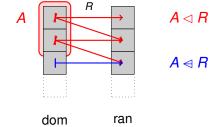
$$R \rhd B := \{x, y \cdot x \mapsto y \in R \land y \notin B \mid x \mapsto y\} \subseteq R$$

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$$A \triangleleft R$$
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■ $R \models B$:= { $x, y \cdot x \mapsto y \in R \land y \notin B \mid x \mapsto y$ } ⊆ R
■ R lational application: $R[A] = ran(A \lhd R)$

Klebanov, Ulbrich - Applications of Formal Verification



Override



$$R \triangleleft S := ((\operatorname{dom} S) \triangleleft R) \cup S$$

$$x \mapsto y \in R \Leftrightarrow S \iff egin{cases} x \mapsto y \in S & ext{if } x \in \operatorname{dom}(S) \ x \mapsto y \in R & ext{if } x
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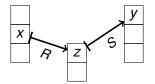
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- Syntax sometimes \oplus instead of \triangleleft
- Compare Updates in Dynamic Logic for KeY.

Forward composition



$$x \mapsto y \in R$$
; $S \iff \exists z \cdot x \mapsto z \in R \land z \mapsto y \in S$

 $x \mapsto y$ is in the composition R; S if there is a transmitting element z with both $x \mapsto z \in R$ and $z \mapsto y \in S$.

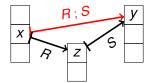


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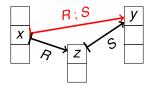


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(There is also backward composition $R \circ S = S$; R)



CONTEXT FileSystemCtx SETS OBJECT CONSTANTS files, dirs, root AXIOMS files \subseteq OBJECT, dirs \subseteq OBJECT, root \in dirs, files \cap dirs $= \emptyset$

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Event-B – Events

Machine (systematic)



```
MACHINE name
SEES context
VARIABLES vars
INVARIANTS inv(vars)
EVENTS
    . . .
END
```

The symbols in context can be used in *inv* even if not mentioned explicitly.

Events



EVENT M

// the following are the parameters, // the input signals, nondeterministic choices ANY $\overline{\textit{prms}}$

// the preconditions, conditions on the input values
WHERE guard(vars, prms)

 $/\!/$ evolution of the program variables when the event "fires" THEN

actions

END

There is one more contruct (WITH) that we omit here.



- "Assignment" x := t
- Variable x and term t must have same type $(\tau(t) = \tau(x))$
- After event, x has value of expression t



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Example:

THEN

$$x := y$$

 $y := x$
END // swaps values of variables x, y .

Unmentioned variable z does not change.

Remember the updates in KeY: $\{x := y || y := x\}$ has same effects.



- $x : | \varphi$ means "choose x such that φ "
- Actions can have more than one resolution
- φ is called the before-after-predicate (BAP)
- variables without tick: before-state
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Example:

$$\mathbf{x},\mathbf{y}:|\mathbf{x}'=\mathbf{y}'\wedge\mathbf{y}'>\mathbf{y}$$

After the action x and y are equal and y is strictly greater than before the action.



Normal form

Every action can be defined as a before-after-predicate

bap(vars, vars', prms)

with

- It was a state of the machines variables before the action
 - *vars* the machine variables after the action
- Image of the parameters of the event
 - *x* := *t* is short for *x* :| *x*′ = *t*
 - $x :\in S$ is short for $x :| x' \in S$

Initialisation



Values of the machine in the beginning?



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- Initial values defined by the special event INITIALISATION.
- before-after-predicate bap_{init} and guard grd_{init} must not refer to vars, there is no "before-state".
- After the first state, only normal events trigger.

Machine Semantics



Machine variables $\overline{vars} := v_1, ..., v_k$ with types $\overline{T} = T_1 \times ... \times T_k$.

A state $\sigma \in \overline{T}$ is a vector, variable assignment.

A trace is a sequence of states $\sigma_0, \sigma_1, \ldots$ such that

- first state σ_0 is result of the initialisation event
- every state σ_i results from an event which operates on σ_{i-1} (for every i > 0).



The semantics of a machine M is the set of all traces possible for M.

Event Parameters



Sources for indeterminism

- indeterministic choices in bap's (cf. :∈, :|)
- event parameters

Event parameter may model:

- content of messages passed around
- indeterministic user input
- unpredictable environment actions
- a number, amount of data to operate with

• . . .

Technically event parameters can be removed and replaced by existential quantifiers.

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State space: $\overline{T} = T_1 \times \ldots \times T_k$



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```
Trace: t \in \mathbb{N} \to \overline{T} with
```

• $\exists prms_{init} \cdot grd_{init}(prms_{init}) \land bap_{init}(t(0), prms_{init})$



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- $\exists prms_{init} \cdot grd_{init}(prms_{init}) \land bap_{init}(t(0), prms_{init})$
- For $n \in \mathbb{N}_1$, there is $e \in EVENTS$ such that $\exists prms_e \cdot grd_e(t(i-1), prms_e) \land bap_e(t(i-1), t(i), prms_e)$



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Semantics (more formally)



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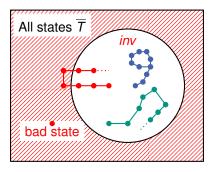
Partial, finite trace trace: $t \in 0..n \rightarrow \overline{T}$

Deadlock: no event *e* can be triggered, i.e. $\forall prms_e \cdot \neg grd_e(t(n), prms_e) \text{ for all events } e.$

Invariants



SAFETY: Do all states reachable by *M* satisfy *inv*?



The red trace violates the invariant in two states.



To show that inv(vars) is an invariant for machine *M*, one proves for every event:

Invariants Guards of the event Before-after-predicate of the thevent ⇒

modified invariant



To show that inv(vars) is an invariant for machine *M*, one proves:

♦ $\forall prms, vars' \cdot grd_{init}(\overline{prms}) \land bap_{init}(\overline{vars'}, \overline{prms}) \rightarrow inv(\overline{vars'})$ (Invariant initally valid)



To show that inv(vars) is an invariant for machine *M*, one proves:

 ∀prms, vars'· grd_{init}(prms) ∧ bap_{init}(vars', prms) → inv(vars') (Invariant initally valid)

Øprms, vars, vars', vars', vars', prms) ∧
 bap_e(vars, vars', prms) → inv(vars')
 for every event e in M.
 (Events preserve invariant)



To show that inv(vars) is an invariant for machine *M*, one proves:

 ∀prms, vars'· grd_{init} ∧ bap_{init} → inv (Invariant initally valid)

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∀prms, vars, vars'.
 inv ∧ grd_e ∧
 bap_e → *inv'* for every event *e* in *M*.
 (Events preserve invariant)

Note: Proof Obligation INV is a sufficient criterion, but not necessary. Necessary for *inductive invariants*.

Inductive Invariant



```
MACHINE Indinv
VARIABLES x INVARIANTS x \in \mathbb{Z} x \ge 0
EVENTS
INITIALISATION \hat{=}
x := 2
STEP \hat{=}
x := 2 * (x - 1)
```

There is only one trace:

$$(2, 2, 2, 2, \ldots)$$

invariant is fulfilled.

Klebanov, Ulbrich - Applications of Formal Verification



Proof obligation INV for event STEP

 $\mathit{inv}(x) \land \mathit{grd}(x) \land \mathit{bap}(x,x') \rightarrow \mathit{inv}(x')$



Proof obligation INV for event STEP

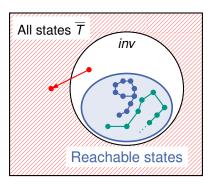
$$\begin{array}{rrrr} \textit{inv}(x) & \wedge & \textit{grd}(x) & \wedge & \textit{bap}(x,x') & \rightarrow & \textit{inv}(x') \\ x \geq 0 & & \wedge & x' = 2*(x-1) & \rightarrow & x' \geq 0 \end{array}$$



Proof obligation INV for event STEP



Proof obligation INV for event STEP



Feasibility Proof Obligation FIS



Show that every action is feasible if the guard is true:

Invariants Guards of the event

 \Rightarrow

 $\exists v' \cdot before-after-predicate$

Feasibility Proof Obligation FIS



The action of an event is is possible if guard is true.

 $\forall \overline{vars}, \overline{prms} \cdot grd_e(\overline{vars}, \overline{prms}) \rightarrow \exists \overline{vars'} \cdot bap(\overline{vars}, \overline{vars'}, \overline{prms})$

Deterministic action: x := t ... nothing to show

Indeterministic action: $x :\in S$... show that $S \neq \emptyset$

Indeterministic action: $x : | \varphi$... show satisfiability of φ

Thus impossible evolutions like x :| false or $x :\in \emptyset$ are avoided

Deadlock Freedom DLKF



Recap:

Deadlock: no event *e* can be triggered, i.e. $\forall prms_e \cdot \neg grd_e(t(n), prms_e)$ for all events *e*.

Deadlock Freedom DLKF



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There is always an event that can trigger:

$$\forall \overline{vars} \cdot inv(\overline{vars}) \Rightarrow \bigvee_{event \ e \in M} \exists \overline{prms} \cdot grd_e(\overline{vars}, \overline{prms})$$

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Again, this is sufficient not necessary. (The invariant may be too weak to imply deadlock freedom)

Event-B – Refinement





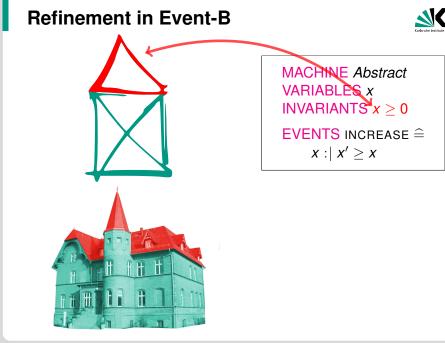








MACHINE Abstract VARIABLES xINVARIANTS $x \ge 0$ EVENTS INCREASE $\hat{=}$ $x : | x' \ge x$







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MACHINE Refined REFINES Abstract VARIABLES x

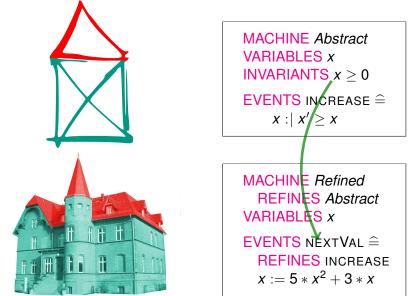




MACHINE Abstract VARIABLES xINVARIANTS $x \ge 0$ EVENTS INCREASE $\widehat{=}$ $x : | x' \ge x$

MACHINE Refined REFINES Abstract VARIABLES xEVENTS NEXTVAL $\widehat{=}$ REFINES INCREASE $x := 5 * x^2 + 3 * x$





Refining Machines



MACHINE Abstract

SEES Context VARIABLES \overline{vars}_A INVARIANTS $inv_A(\overline{vars}_A)$ EVENTS INITIALISATION $\stackrel{\frown}{=}$... EVT_A $\stackrel{\frown}{=}$...

END

```
MACHINE Refined
  REFINES Abstract
SEES Context
VARIABLES vars<sub>R</sub>
INVARIANTS
    inv_{R}(vars_{A}, vars_{R})
EVENTS
  INITIALISATION \widehat{=} ...
  EVT_B \cong
    REFINES EVT⊿...
FND
```



Every machine *M* defines:

- a state space S_M spanned by the types of vars_M
- the initialisation $I_M \subseteq S_M$
- the transition relations $E_{M;evt} \in S_M \leftrightarrow S_M$ (for event *evt*)

$$S_M = \tau(v_1) \times \ldots \times \tau(v_k)$$
 (with $vars_M = v_1, \ldots, v_k$)



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Details

 $S_{M} = \tau(v_{1}) \times \ldots \times \tau(v_{k}) \quad (\text{with } vars_{M} = v_{1}, \ldots, v_{k})$ $I_{M}(p) = \{s \in S_{M} \mid grd_{init}(p) \land bap_{init}(s', p)\}$ $I_{M} = \bigcup_{p} I_{M}(p)$ $E_{M;evt}(p) = \{(s \mapsto s') \mid grd_{evt}(s, p) \land bap_{evt}(s, s', p)\}$



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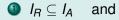
Simple Refinement – Definition



Every trace of the refined machine R is a trace of the abstract machine A.

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Let R, A be two machines with the same state space S. R is called a refinement of A if



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 $E_{R;evt_R} \subseteq E_{A;evt_A} \quad \text{for each event}$

(evt_R is the event in *R* that refines event evt_A from *A*)

Loss of behaviour



Why is this problematic?

```
MACHINE A ....
EVENTemergencyStop ≙
WHERE true THEN heavyMachine := stop
END
```

refined by

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MACHINE R...EVENTemergencyStop \cong REFINES emergencyStopWHERE false THEN heavyMachine := stopEND
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 $E_{R;evt} = \varnothing \implies R \text{ refines } A$



Every trace for A has a refining trace for R.



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More precisely

For every trace in *A* with triggered events $evt_{A,1}$, $evt_{A,2}$, ..., there is a trace in *R* with triggered events $evt_{R,1}$, $evt_{R,2}$, ... and $evt_{R,i}$ refines $evt_{A,i}$.



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④ dom $(E_{A;evt_A}) \subseteq dom(E_{R;evt_R})$ for each event



More general notion of refinement

What if abstract machine A and refinement R have different state spaces S_A and S_R ?



More general notion of refinement

What if abstract machine A and refinement R have different state spaces S_A and S_R ?

→ Couple abstract and refined state space.

 $\mathcal{C} \in \mathcal{S}_{\mathcal{R}} \leftrightarrow \mathcal{S}_{\mathcal{A}}$ Coupling invariant / Gluing invariant



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Example

MACHINE AbstractFileSys VARIABLES openFiles INVARIANTS openFiles ⊆ FILES MACHINE RefinedFileSys VARIABLES openModes INVARIANTS openModes ⊆ FILES × MODES



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$$C = \{r \mapsto a \mid a = \operatorname{dom}(r)\} = \{f, m \cdot (f \mapsto m) \mapsto m\}$$



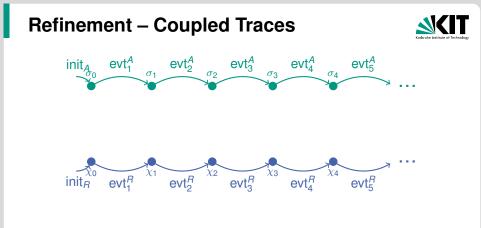
Sensible to assume *C* a total relation:

$$\mathcal{C}\in \mathcal{S}_{\mathcal{R}} \nleftrightarrow \mathcal{S}_{\mathcal{A}}$$

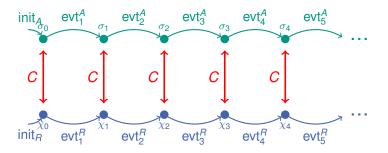
• Often, coupling is a total function:

$$\mathcal{C}\in\mathcal{S}_{\mathcal{R}} o\mathcal{S}_{\mathcal{A}}$$

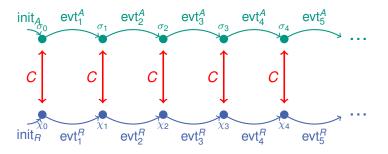
Define *one* abstraction for any detailed state. BUT sometimes, several possible abstractions per concrete state sensible.







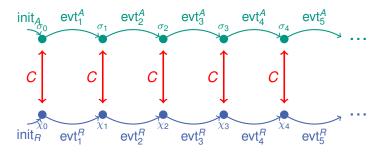




Refinement: R refines A

For every concrete trace $(\chi_0, \chi_1, ...)$ of *R* with events $(evt_1^R, evt_2^R, ...)$ there exists an abstract trace $(\sigma_0, \sigma_1, ...)$ with events $(evt_1^A, evt_2^A, ...)$ such that

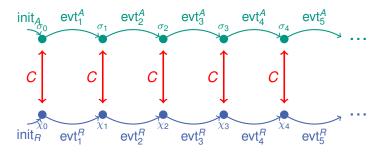




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 $I_R \subseteq C^{-1}[I_A] \text{ and }$

 $(\forall x, y \cdot x \mapsto y \in R^{-1} \Leftrightarrow y \mapsto x \in R$, inverse relation)

Refinement – Definition



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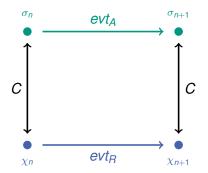
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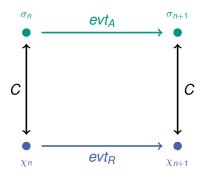
2)
$$E_{R;evt_R} \subseteq C$$
 ; $E_{A;evt_A}$; C^{-1} for each event.

 $(\forall x, y \cdot x \mapsto y \in R^{-1} \Leftrightarrow y \mapsto x \in R$, inverse relation)



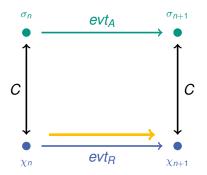






 $E_{R;evt_R} \subseteq C$; $E_{A;evt_A}$; C^{-1}



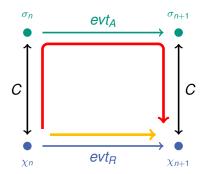


 $E_{R;evt_R} \subseteq C$; $E_{A;evt_A}$; C^{-1}

Klebanov, Ulbrich - Applications of Formal Verification

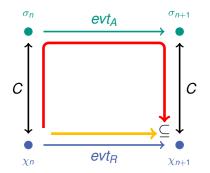
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 $E_{R;evt_R} \subseteq C$; $E_{A;evt_A}$; C^{-1}





 $E_{R;evt_R} \subseteq C$; $E_{A;evt_A}$; C^{-1}

Specifying Coupling



The coupling invariant is specified as part of the invariant of the refining machine.



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The invariant of a refinement is allowed to refer to variables of its abstraction.



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Example (from slide 72)

MACHINE AbstractFileSys VARIABLES openFiles INVARIANTS openFiles ⊆ FILES MACHINE RefinedFileSys VARIABLES openModes INVARIANTS openModes ⊆ FILES × MODES



The coupling invariant is specified as part of the invariant of the refining machine.

The invariant of a refinement is allowed to refer to variables of its abstraction.

Example (from slide 72)

MACHINE AbstractFileSys VARIABLES openFiles INVARIANTS openFiles ⊆ FILES MACHINE RefinedFileSys VARIABLES openModes INVARIANTS openModes ⊆ FILES × MODES openFiles = dom(openModes)

Proof Obligation GRD



Proof that event guard in refinement is **stronger** than in abstract machine.

 \implies Abstraction is enabled when refinement is.

Abstract invariants Concrete invariants Concrete event guard

Abstract event guard

Proof Obligation GRD



Proof that event guard in refinement is **stronger** than in abstract machine.

 \implies Abstraction is enabled when refinement is.

Abstract invariants Concrete invariants Concrete event guard

 \implies

Abstract event guard

 $\forall vars_A, vars_R \cdot$

 $\mathit{inv}_A(\overline{\mathit{vars}_A}) \land \mathit{inv}_R(\overline{\mathit{vars}_A}, \overline{\mathit{vars}_R}) \land \mathit{grd}_R(\overline{\mathit{vars}_R})$

 \Rightarrow grd_A(vars_A)

(Version w/o parameters, see literature for full version)



Show that refined action *simulates* abstract actions

- Abstract invariants Concrete invariants Concrete event guard Concrete before-after-predicate
 - Abstract before-after-predicate



Show that refined action *simulates* abstract actions

Abstract invariants Concrete invariants Concrete event guard Concrete before-after-predicate

Abstract before-after-predicate

Rem $E_{R;evt_R} \subseteq C$; $E_{A;evt_A}$; C^{-1}



Show that refined action *simulates* abstract actions

Abstract invariants

Concrete invariants

- Concrete event guard
- Concrete before-after-predicate

Abstract before-after-predicate

- **Rem** $E_{R;evt_R} \subseteq C$; $E_{A;evt_A}$; C^{-1}
- **Obs** The coupling invariant is only used for the before-state not for the after-state.



Show that refined action *simulates* abstract actions

Abstract invariants

Concrete invariants

- Concrete event guard
- Concrete before-after-predicate

Abstract before-after-predicate

Rem
$$E_{R;evt_R} \subseteq C$$
 ; $E_{A;evt_A}$; C^{-1}

- **Obs** The coupling invariant is only used for the before-state not for the after-state.
 - ? Why?

Proof Obligation SIM



Show that refined action *simulates* abstract actions

Abstract invariants

Concrete invariants

- Concrete event guard
- Concrete before-after-predicate

Abstract before-after-predicate

Rem
$$E_{R;evt_R}\subseteq C$$
 ; $E_{A;evt_A}$; C^{-1}

- **Obs** The coupling invariant is only used for the before-state not for the after-state.
 - ? Why?
 - ! Already proven condition INV implies invariant for after-state.



- Witnesses for parameters dropped in refinements
- Termination issues (variants)
- Extended/Not extended events
- Event merging
- Sequential refinement



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Byzantine Agreement – A case study verified with Event-B

Based on:

Roman Krenický and Mattias Ulbrich. *Deductive Verification of a Byzantine Agreement Protocol.* Technical report (2010-7). Karlsruhe Institute of Technology, Department of Informatics, 2010

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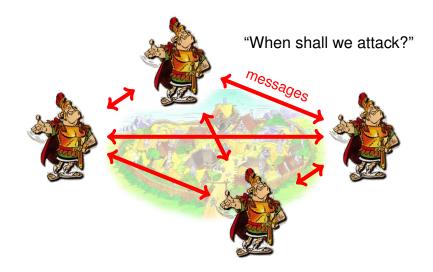




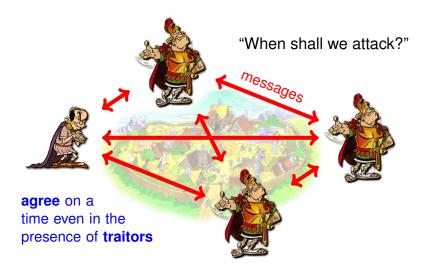


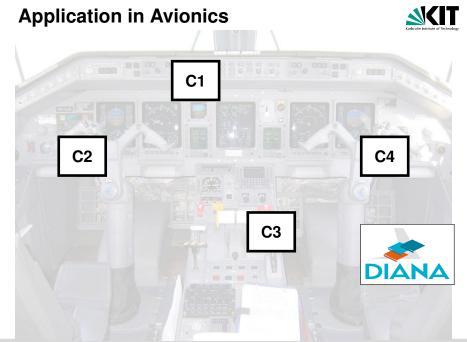


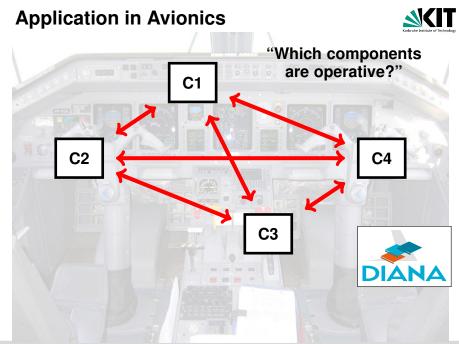










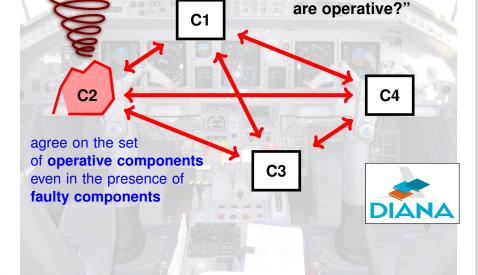


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Application in Avionics





"Which components



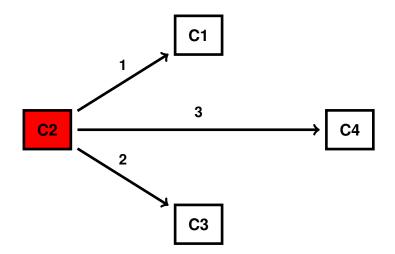






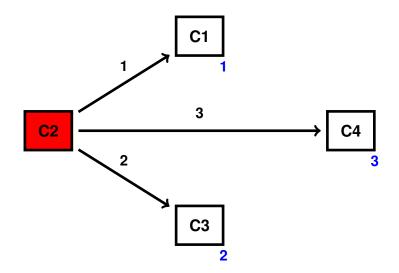




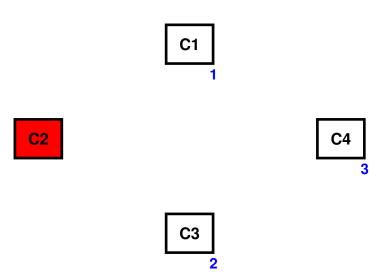


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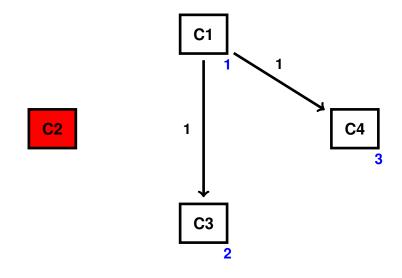




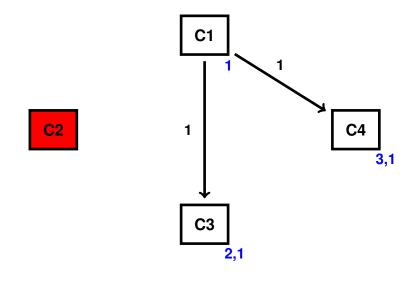






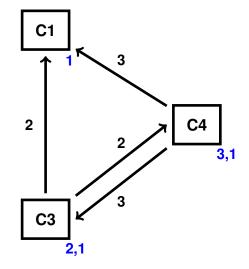






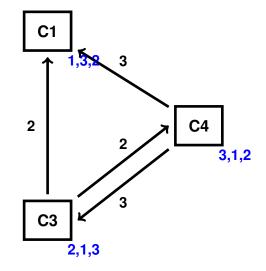






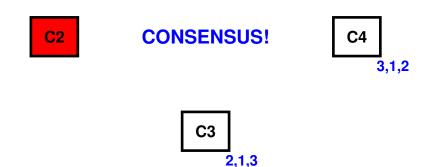












SS 2015

C4

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C1

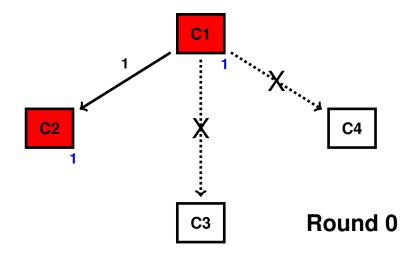


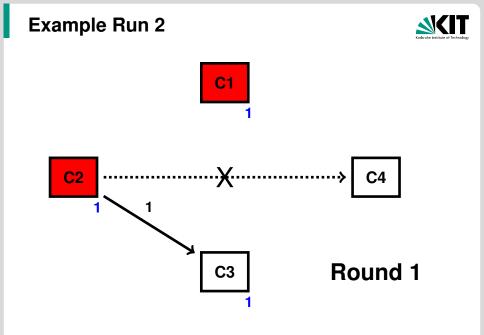
Example Run 2

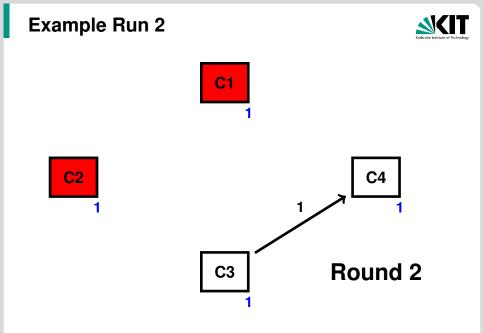


Example Run 2











Verification Goals:

Validity If the transmitter *tt* is non-faulty, then all non-faulty receivers agree on the value sent by *tt*.

Agreement Any two non-faulty receivers agree on the value assigned to *tt*.

Byzantine Agreement Algorithm



Round 0: Transmitter sends signed message to all receivers.



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Round *n*: Component receive messages, verify signatures, sign messages and pass them on.



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Round *n*: Component receive messages, verify signatures, sign messages and pass them on.

GOAL: Prove that this algorithm has the "validity" and "agreement" properties.

Verification



Quote

We know of no area in computer science or mathematics in which informal reasoning is more likely to lead to errors than in the study of this type of algorithm.

Taken from: The Byzantine Generals Problem

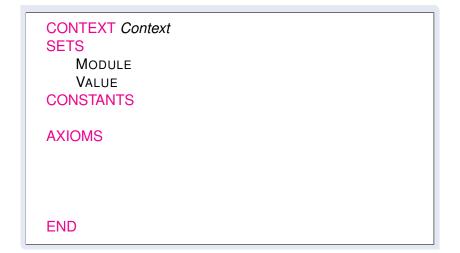
Leslie Lamport, Robert Shostak, and Marshall Pease ACM Transactions on Programming Languages and Systems Volume 4, pp. 383–401,1982. **Context for Byzantine Agreement**





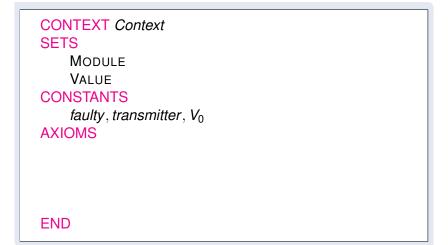
Context for Byzantine Agreement





Context for Byzantine Agreement





Context for Byzantine Agreement



```
CONTEXT Context
SETS
    MODULE
    VALUE
CONSTANTS
    faulty, transmitter, V_0
AXIOMS
    faulty \subseteq MODULE
    transmitter ∈ MODULE
    V_0 \in \mathsf{VALUE}
    finite(faulty)
FND
```



MACHINE Messages SEES Context

VARIABLES

INVARIANTS

. . .



MACHINE Messages SEES Context VARIABLES messages, round, collected INVARIANTS



MACHINE Messages SEES Context VARIABLES messages, round, collected INVARIANTS ty_mess : messages ⊆ MODULE × MODULE × VALUE

...

messages messages being sent in the current round



messages messages being sent in the *current* round *round* the number of the current round



```
\begin{array}{l} \mbox{MACHINE Messages} \\ \mbox{SEES Context} \\ \mbox{VARIABLES messages, round, collected} \\ \mbox{INVARIANTS} \\ \mbox{ty\_mess: messages} \subseteq \mbox{MODULE} \times \mbox{MODULE} \times \mbox{VALUE} \\ \mbox{ty\_round: round} \in \mbox{N} \\ \mbox{ty\_collected: collected} \in \mbox{MODULE} \rightarrow \mbox{P}(\mbox{VALUE}) \\ \end{array}
```





messages messages being sent in the *current* round *round* the number of the current round *collected* values observed in previous rounds

END



```
MACHINE Messages SEES Context
VARIABLES messages, round, collected
INVARIANTS...
EVENTS
Initialisation ≙ ...
EVENT ROUND ≙
act1 : round := round + 1
END
```



```
MACHINE MessagesSEES ContextVARIABLES messages, round, collectedINVARIANTS...EVENTSInitialisation \widehat{=} ...EVENT ROUND \widehat{=}<br/>act1 : round := round + 1<br/>act2 : messages :\in \mathbb{P}(MODULE × MODULE × VALUE)END
```





messages messages being sent in the *current* round *round* the number of the current round

collected values observed in previous rounds

```
MACHINE MessagesSEES ContextVARIABLES messages, round, collectedINVARIANTS...EVENTSInitialisation \cong ...EVENT ROUND \congact1 : round := round + 1act2 : messages :< \mathbb{P}(MODULE \setminus \{transmitter\} \times MODULE \times VALUE)act3 : collected := \lambda m \cdot collected(m) \cupEND
```



messages messages being sent in the *current* round *round* the number of the current round

collected values observed in previous rounds

```
\label{eq:main_state} \begin{array}{l} \text{MACHINE Messages} & \text{SEES Context} \\ \text{VARIABLES messages, round, collected} \\ \text{INVARIANTS...} \\ \\ \hline \text{EVENTS} \\ \hline \text{Initialisation} \triangleq \dots \\ \hline \text{EVENT ROUND} \triangleq \\ & act1 : round := round + 1 \\ & act2 : messages : \in \mathbb{P}(\text{MODULE} \setminus \{\text{transmitter}\} \times \text{MODULE} \times \text{VALUE}) \\ & act3 : collected := \lambda m \cdot collected(m) \cup \{v \mid (s, m, v) \in \text{messages}\} \\ \hline \text{END} \end{array}
```

First refinement: signed messages



All messages are signed in a trustworthy manner:

No forgery possible \implies Consider only **relayed** messages.

First refinement: signed messages



All messages are signed in a trustworthy manner:

No forgery possible \implies Consider only **relayed** messages.

round k: $s \xrightarrow{v} r$

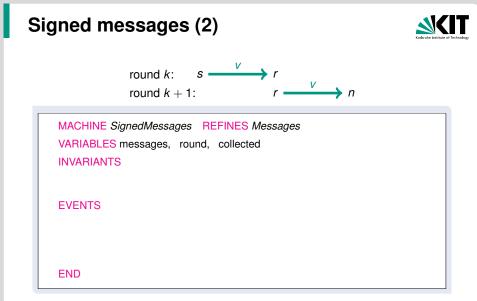
First refinement: signed messages

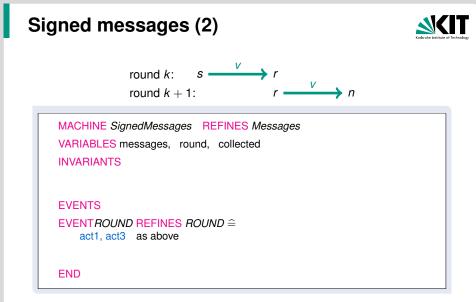


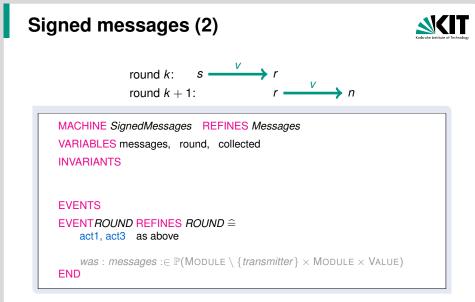
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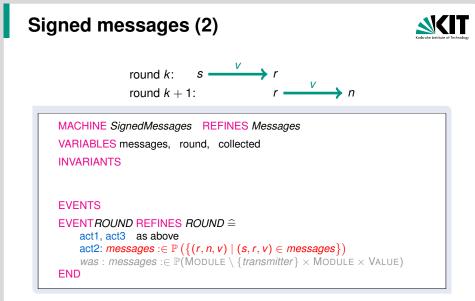
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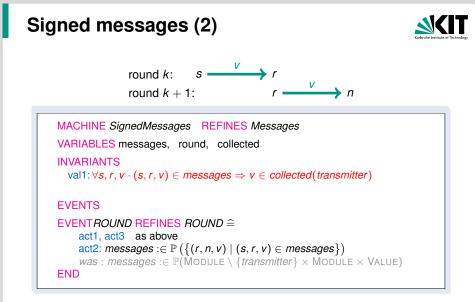


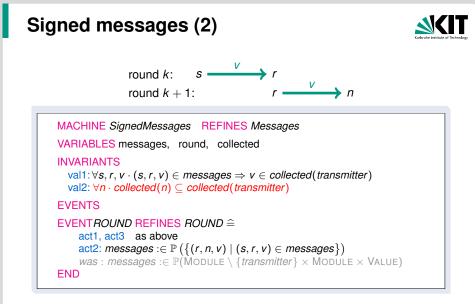




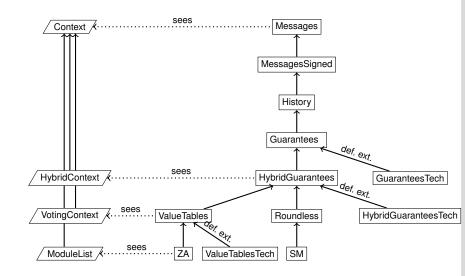




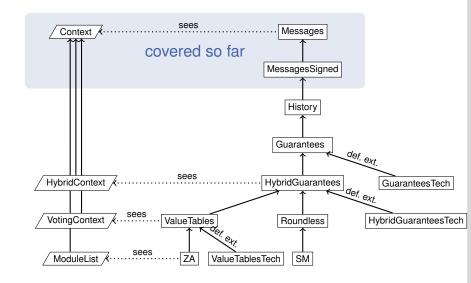






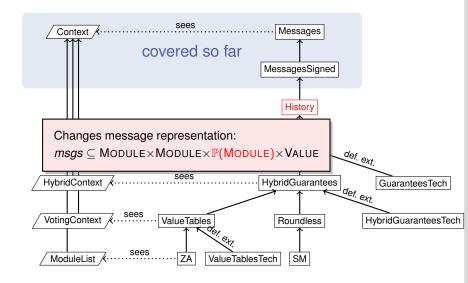




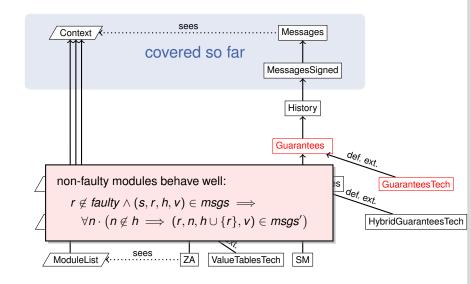


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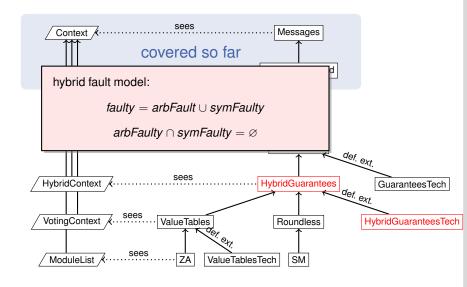




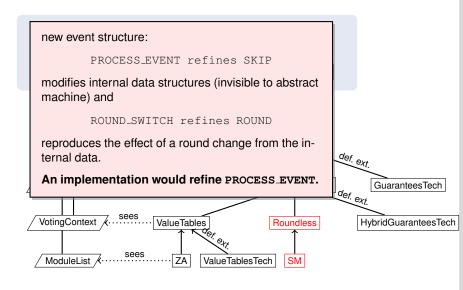




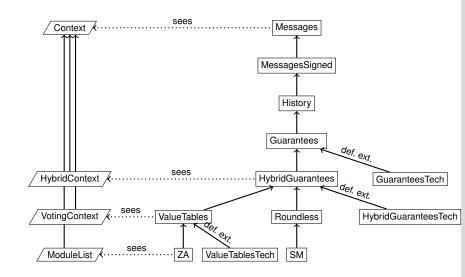












Agreement!



In machine Guarantees:

$\begin{aligned} \text{round} \geq & \textit{card}(\textit{faulty}) + 1 \implies \\ & (\forall n, m \cdot n \notin \textit{faulty} \land m \notin \textit{faulty} \Rightarrow \\ & \textit{collected}(n) = & \textit{collected}(m)) \end{aligned}$

Agreement!



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In machine HybridGuarantees:

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Verification Effort



Numbers

Size:4 contexts, 12 machines, 106 invariantsLabour:approx. 4 person monthsProofs:322 proof obligationsAutomation:74/322, 23%