

A Temporal Logic for Programs

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Dynamic Logic (DL)

- **“talks” about final state of program**
- **not useful for non-terminating programs**
- **does not allow reasoning about temporal properties**
- **“waste”: symbolic execution computes all intermediate program states (trace) but throws away everything except for the final state!**

First approach [Beckert & Schlager, 2001]

- Extension of DL with additional modalities “preserves”, “throughout”, and “at least once”
- **Example:** $x > 0 \rightarrow [[\text{while } (\text{true}) \ x++]] x > 0$
- **Calculus for JavaCard-DL in [Beckert & Mostowski, 2003]**
implemented in KeY

- Each modality strictly bound to one program
- Modalities cannot be combined as usual in temporal logics

Example: $\Box(x < 0 \rightarrow \Diamond x > 0)$

“It must hold in all states that if x becomes negative eventually it will become positive”

- Expressing above property requires new modality

- **Combine ideas from Dynamic Logic and Temporal Logic**
- **Decouple modal operators and programs**
- **Program defines structure which temporal formula is evaluated in**
- **Example:**
$$\forall x.(i \doteq x \rightarrow \llbracket \text{while (true) } i++ \rrbracket \square (x < 0 \rightarrow \diamond x > 0))$$
- **Semantics of $\llbracket p \rrbracket$ is the (in-)finite trace of program p**

Syntax of Dynamic Temporal Logic (DTL)

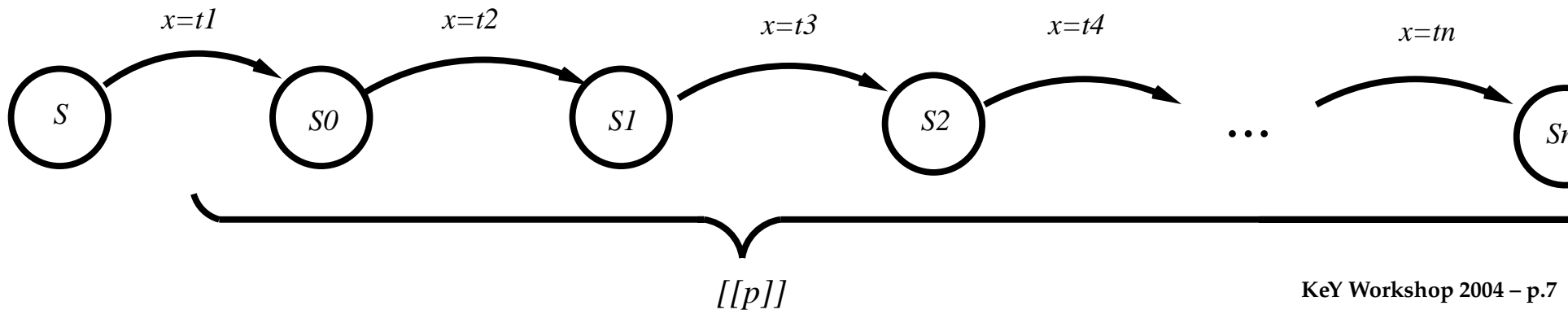


- if $\phi \in F(FOL)$ then $\phi \in F(DTL)$
- if $\phi, \psi \in F(DTL)$, p is a program, and x is a variable then
 - $\Box\phi, \Diamond\phi, \phi\mathbf{U}\psi \in F(DTL)$
 - $\neg\phi, \phi \wedge \psi \in F(DTL)$
 - $\llbracket p \rrbracket\phi \in F(DTL)$ if ϕ contains an unbound modal operator
 - $\forall x.\phi \in F(DTL)$

Semantics of DTL



- $I_s(\llbracket p \rrbracket) = (s_0, s_1, \dots, s_n)$ where s is initial state
- $I_s(x=t) = (s_x^t)$ (transitions only by assignments)
- $I_s(u; v) = I_s(u) \circ I_{last(I_s(u))}(v)$
- for $\phi \in F(FOL)$: $s \models \llbracket p \rrbracket \phi$ iff $s \models \phi$
- $s \models \llbracket p \rrbracket \phi U \psi$ iff for a s_i with $0 \leq i \leq n$ holds $s_i \models (s_{i+1}, s_{i+2}, \dots, s_n)$ and for all s_j with $0 \leq j < i$ holds $s_j \models (s_{j+1}, s_{j+2}, \dots, s_{i-1})$
- $s \models \llbracket p \rrbracket \Box \phi$ iff for all s_i with $0 \leq i \leq n$ holds $s_i \models (s_{i+1}, s_{i+2}, \dots, s_n)$
- $s \models \llbracket p \rrbracket \Diamond \phi$ iff for a s_i with $0 \leq i \leq n$ holds $s_i \models (s_{i+1}, s_{i+2}, \dots, s_n)$



- $\Box false$ holds only in final states
- DL modalities can be expressed
 - $[p]\phi \equiv \llbracket p \rrbracket \Box(\Box false \rightarrow \phi)$
 - $\langle p \rangle \phi \equiv \llbracket p \rrbracket \Diamond(\Box false \wedge \phi)$
- $\llbracket i=1; \text{while (true) } i++ \rrbracket \forall x. \Box(i \doteq x \rightarrow \Diamond i \doteq 2x)$

Assignment Rule for “throughout”

$$\frac{\Gamma \vdash \phi, \Delta \quad \Gamma \vdash \{x := t\} [[\omega]] \phi, \Delta}{\Gamma \vdash [[x = t; \omega]] \phi, \Delta}$$

Assignment Rule for \square

$$\frac{\Gamma \vdash \{x := t\} [[\omega]] \phi, \Delta \quad \Gamma \vdash \{x := t\} [[\omega]] \square \phi, \Delta}{\Gamma \vdash [[x = t; \omega]] \square \phi, \Delta}$$

Concatenation rule for “at least once

$$\frac{\Gamma \vdash \langle\langle\alpha\rangle\rangle\phi, \langle\alpha\rangle\langle\langle\beta\rangle\rangle\phi, \Delta}{\Gamma \vdash \langle\langle\alpha;\beta\rangle\rangle\phi, \Delta}$$

General concatenation rule for DTL not possible!

Rule for special case $\phi \in F(FOL)$

$$\frac{\Gamma \vdash \llbracket\alpha\rrbracket\Diamond\phi, \langle\alpha\rangle\llbracket\beta\rrbracket\Diamond\phi, \Delta}{\Gamma \vdash \llbracket\alpha;\beta\rrbracket\Diamond\phi, \Delta}$$

Improving the previous concatenation rule



$$\frac{\Gamma \vdash \llbracket \alpha \rrbracket \diamond \phi, \langle \alpha \rangle \llbracket \beta \rrbracket \diamond \phi, \Delta}{\Gamma \vdash \llbracket \alpha; \beta \rrbracket \diamond \phi, \Delta}$$

Rule requires duplicate computation of trace of α !

Similar to the rule for “at least once”



$$\frac{\Gamma \vdash \llbracket \alpha \rrbracket \diamond \phi, \langle \alpha \rangle \llbracket \beta \rrbracket \diamond \phi, \Delta}{\Gamma \vdash \llbracket \alpha; \beta \rrbracket \diamond \phi, \Delta}$$

Rule requires duplicate computation of trace of α !

Similar to the rule for “at least once”

Improved rule

$$\frac{\Gamma \vdash \llbracket \alpha \rrbracket \diamond (\phi \vee (\Box \text{false} \wedge \llbracket \beta \rrbracket \diamond \phi)), \Delta}{\Gamma \vdash \llbracket \alpha; \beta \rrbracket \diamond \phi, \Delta}$$

Towards a CTL-Version

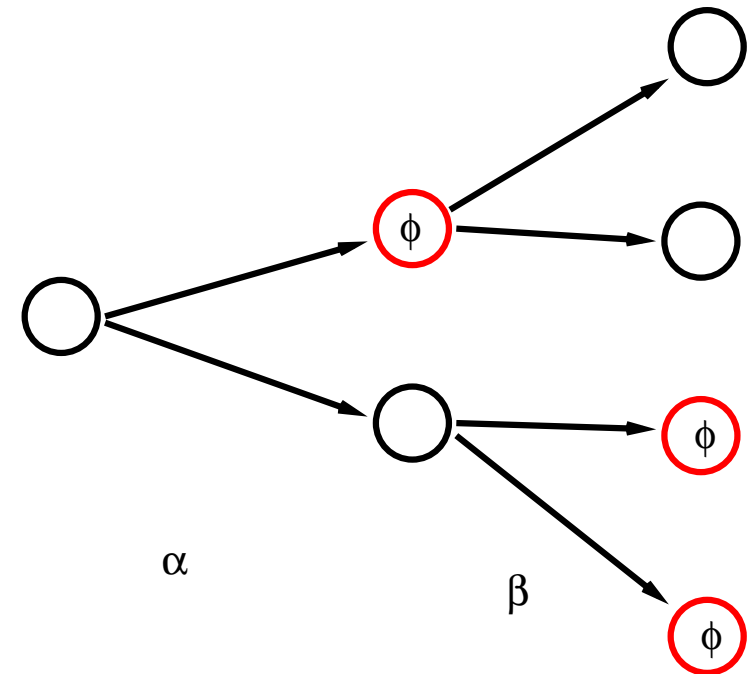


Now we consider non-deterministic languages!

Semantics of \diamond ?

there is a path such that $\diamond\phi$ or **for all** paths $\diamond\phi$

$$\frac{\Gamma \vdash [[\alpha]]\diamond\phi, \langle\alpha\rangle[[\beta]]\diamond\phi, \Delta}{\Gamma \vdash [[\alpha;\beta]]\diamond\phi, \Delta}$$



Towards a CTL-Version



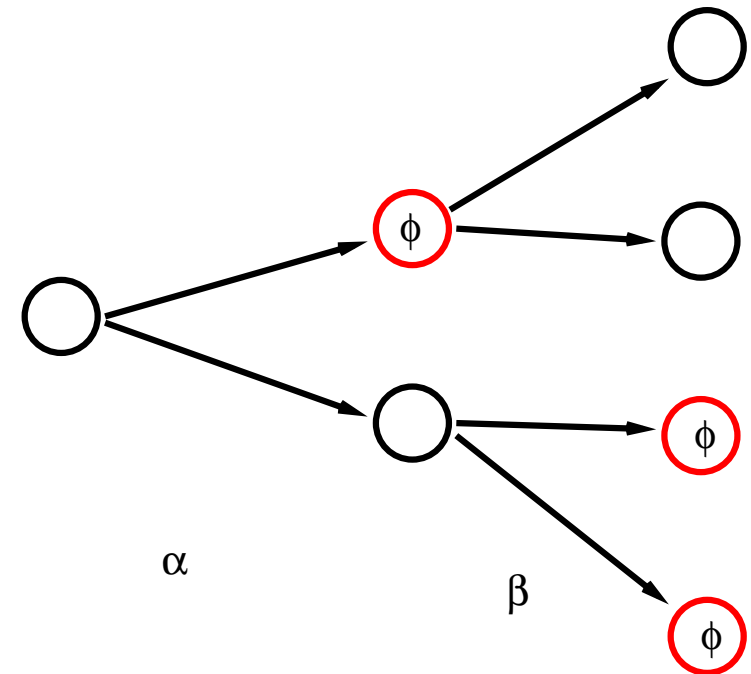
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Semantics of \diamond ?

there is a path such that $\diamond\phi$ or for all paths $\diamond\phi$

$$\Gamma \vdash [[\alpha]]\diamond\phi, \langle\alpha\rangle true \wedge [\alpha][[\beta]]\diamond\phi, \Delta$$

$$\Gamma \vdash [[\alpha;\beta]]\diamond\phi, \Delta$$



Towards a CTL-Version



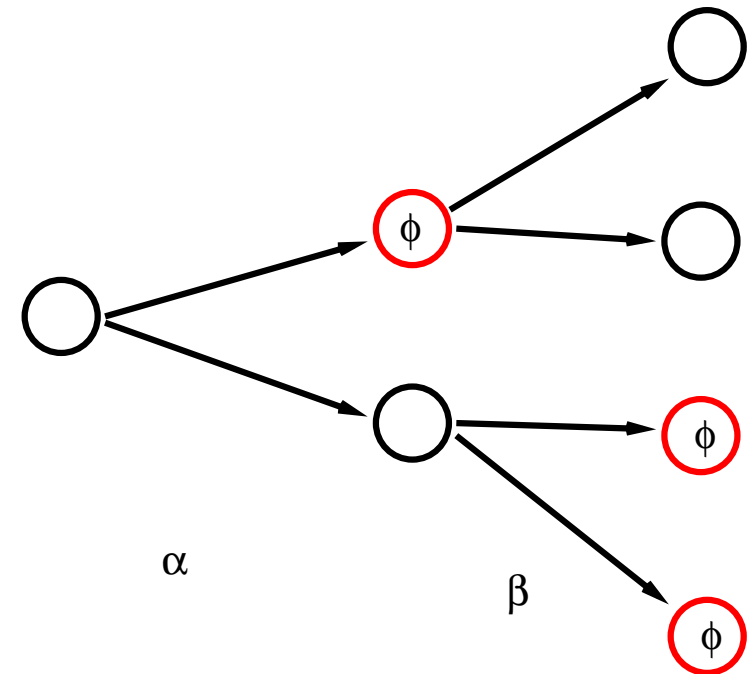
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$$\Gamma \vdash [[\alpha]]\diamond(\phi \vee (\Box false \wedge [[\beta]]\diamond\phi)), \Delta$$

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Towards a CTL-Version



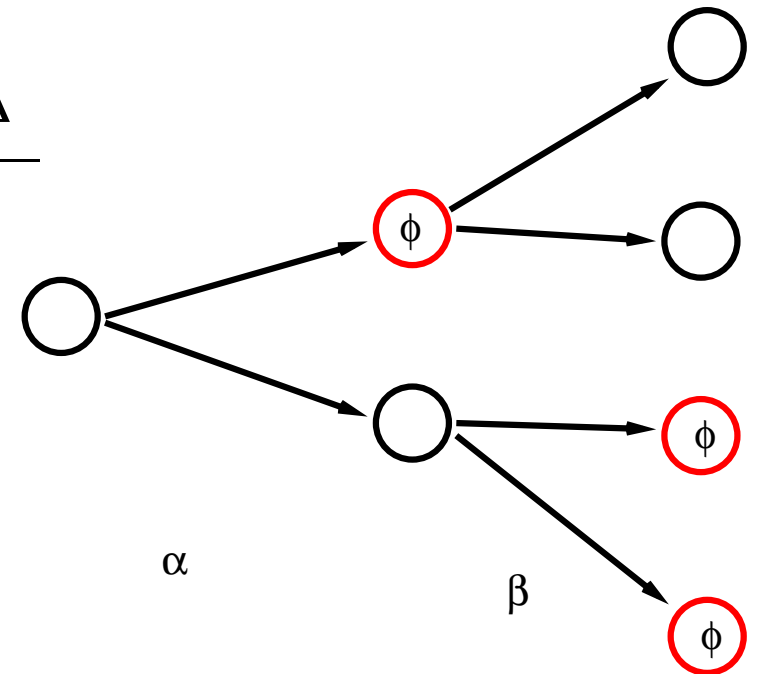
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Semantics of \diamond ?

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$$\Gamma \vdash [[\alpha]]Q(\diamond(\phi \vee (\Box false \wedge [[\beta]]Q\diamond\phi))), \Delta$$

$$\Gamma \vdash [[\alpha;\beta]]Q\diamond\phi, \Delta$$



Rules for Loops



- Similar to rules for μ -calculus
- Idea: identify repeats in the proof

Example:

$$\begin{array}{c}
 \frac{i \dot{=} c, c > 0 \vdash \llbracket p \rrbracket \square (i \dot{=} x_0 \rightarrow \diamond i \dot{=} 2x_0)}{i \dot{=} i' + 1, i - 1 \dot{=} c, c + 1 > 0 \vdash \llbracket p \rrbracket \square (i \dot{=} x_0 \rightarrow \diamond i \dot{=} 2x_0)} \text{Subst.}\{c \leftarrow c + 1\} \\
 \frac{A \quad \frac{i \dot{=} i' + 1, i' \dot{=} c, c > 0 \vdash \llbracket p \rrbracket \square (i \dot{=} x_0 \rightarrow \diamond i \dot{=} 2x_0)}{i \dot{=} c, c > 0 \vdash \llbracket p \rrbracket \square (i \dot{=} x_0 \rightarrow \diamond i \dot{=} 2x_0)} \text{Assignm.}}{i \dot{=} c, c > 0 \vdash \llbracket p \rrbracket \square (i \dot{=} x_0 \rightarrow \diamond i \dot{=} 2x_0)} \text{Cut\&Weakening} \\
 \frac{i \dot{=} 1 \vdash i > 0 \quad \frac{i \dot{=} c, c > 0 \vdash \llbracket p \rrbracket \square (i \dot{=} x_0 \rightarrow \diamond i \dot{=} 2x_0)}{i \dot{=} c, c > 0 \vdash \llbracket p \rrbracket \square (i \dot{=} x_0 \rightarrow \diamond i \dot{=} 2x_0)} \text{Gen.}}{i \dot{=} 1 \vdash \llbracket p \rrbracket \square (i \dot{=} x_0 \rightarrow \diamond i \dot{=} 2x_0)} \\
 \frac{i \dot{=} 1 \vdash \llbracket p \rrbracket \square (i \dot{=} x_0 \rightarrow \diamond i \dot{=} 2x_0)}{i \dot{=} 1 \vdash \llbracket \text{while (true) } i++ \rrbracket \forall x. \square (i \dot{=} x \rightarrow \diamond i \dot{=} 2x)}
 \end{array}$$

with

$$A := i \dot{=} i' + 1, i' \dot{=} c, c > 0 \vdash \llbracket p \rrbracket (i \dot{=} x_0 \rightarrow \diamond i \dot{=} 2x_0)$$

- **Finishing work on rules for loops**
- **DTL for PROMELA⁺**
 - **non-deterministic constructs**
 - **communication via channels**
 - **processes and dynamic process creation**
- **Translating statecharts into PROMELA⁺ for verification of temporal properties**