

Verification of Schorr-Waite

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Algorithm characteristics:

- ▶ Graph-Marking algorithm designed by H.Schorr and W.Waite

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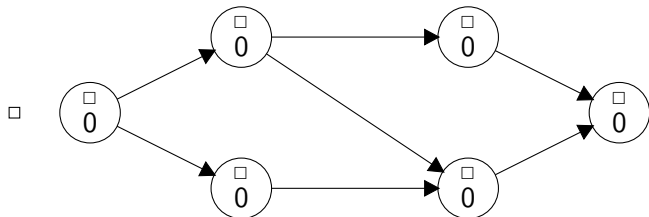
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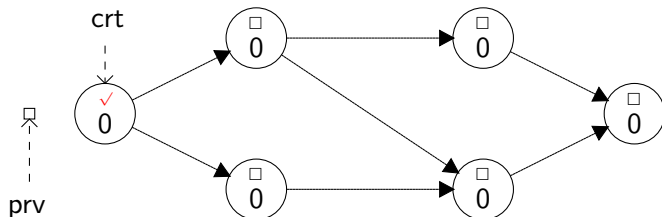
Benchmark for verification methods dealing with linked structures

Schorr-Waite Algorithm



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prv = null; crt = start;
crt.setMark(true);
while (start != crt ||
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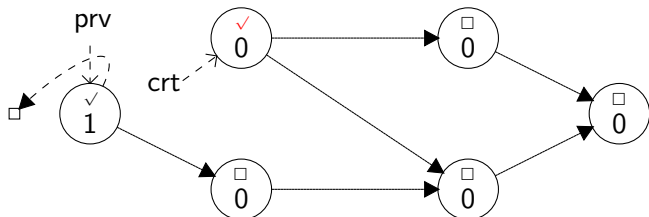
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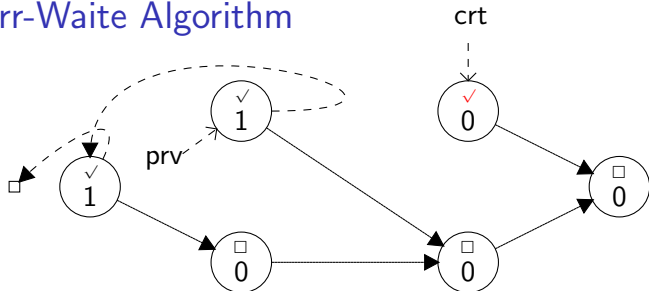
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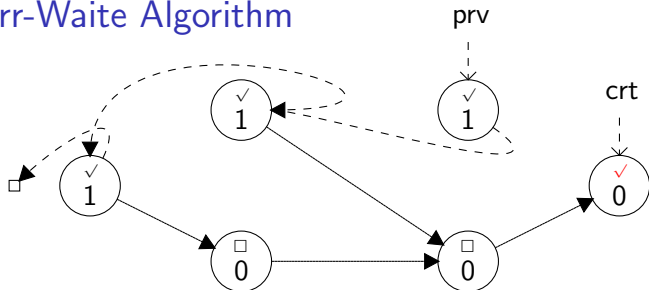

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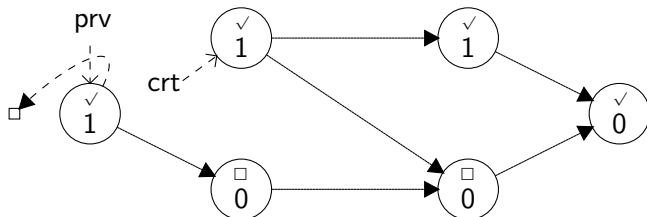
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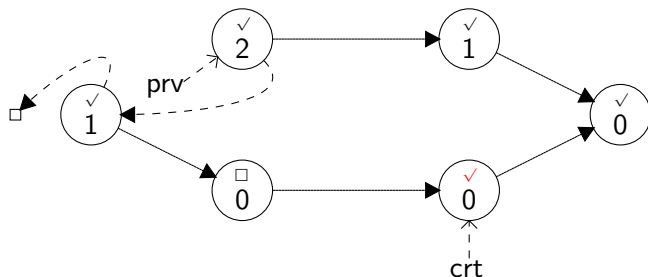

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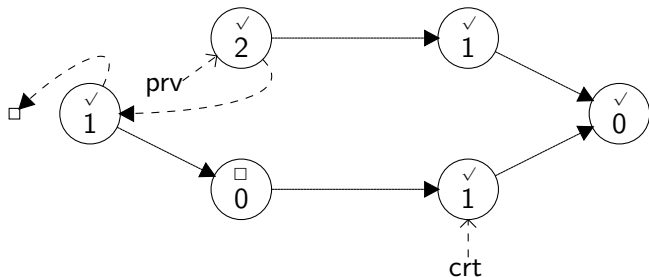
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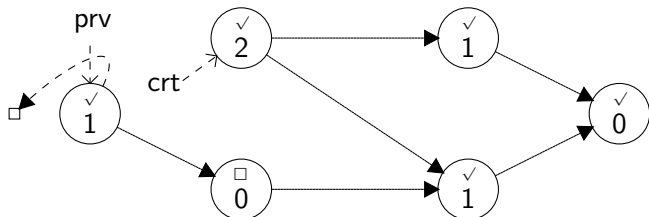
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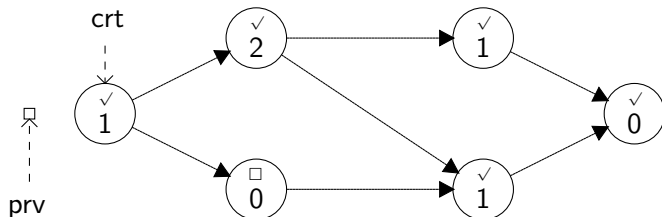
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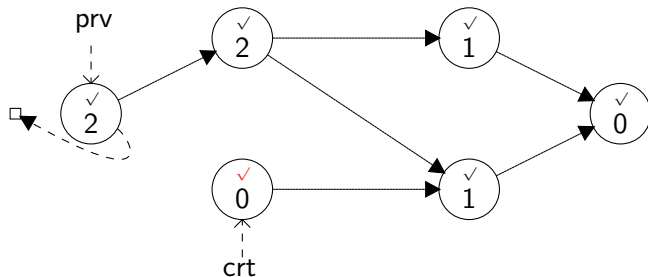
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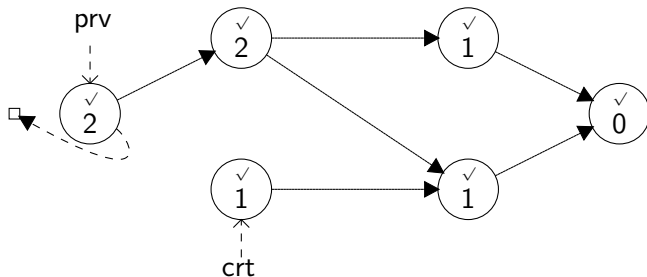

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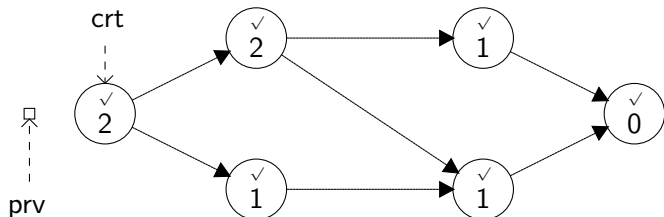
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Reasoning in presence of non-rigid symbols

Problem: Assume a method `getA` returning the value of attribute `a`

$$\{x.b:=c \mid\mid o.a:=3\}.o.getA() = 3$$

\implies

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- ▶ Update simplification too coarse (not possible)

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- ▶ Update simplification too coarse (not possible)
- ▶ Need to know the definition of method `getA`

Non-rigid symbols with explicit dependencies

$\langle symbolName \rangle \{ \langle locationDescriptor \rangle \} : T_1 \times \dots \times T_n (\rightarrow T_{n+1})_{opt}$

Example:

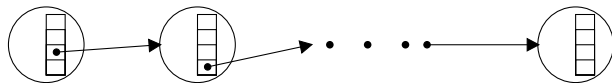
$nonNull \{ \backslash for T t; \backslash for int i; t.a[i] \} : T$

Possible applications:

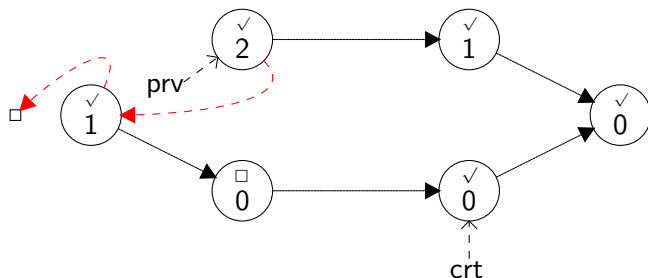
- ▶ modelling queries
- ▶ auxiliary functions like permutation predicate

Modelling reachability

Let C denote a class with a field a of array type $C[]$



Backtracking Path Encoding



Use again a non-rigid predicate: `onPath[...](prv,u,step)`

— KeY —

```
\find ( onPath[\for (hov; iv) hov.children[iv];
        \for (hov2) hov2.children.length;
        \for (hov3) hov3.nextChild](t1, t2, n) )
\replacewith( n >= 0 \& ( ( t1 = t2 \& n = 0 ) |
    ( t1 != null \& t1.nextChild > 0 \&
      t1.nextChild <= t1.children.length \&
      onPath[...](t1.children[t1.nextChild-1], t2, n-1))))
```

— KeY —

Proofobligation

```
inReachableState & ... &
\forall HeapObject ho; (!ho = null ->
  ho.visited = FALSE & ho.nextChild = 0)
->
\[{ sw.mark(startNode); }\]
  \forall HeapObject x; \forall int n;
    ( !x = null &
      reach[\for (HeapObject x; int i) x.children[i];
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          ](startNode, x, n)
      -> ( x.visited = TRUE &
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            x.children[i] = childrenPre(x,i)) ))
```

All nodes reachable from the starting node (not changed by mark)

1. are marked visited

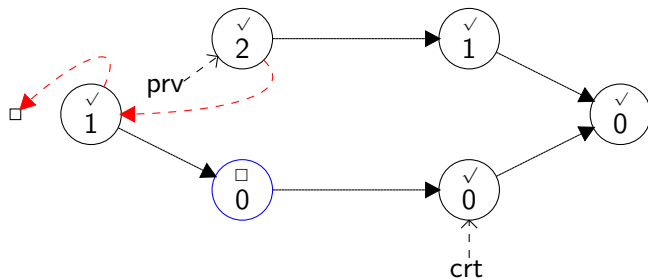
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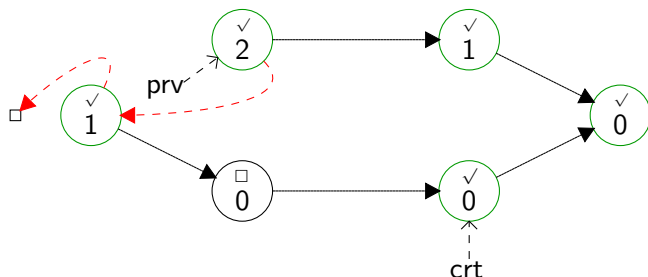
1. are marked visited
2. have same children as before (the graph structure unchanged)

Loop Inv. – Unvisited nodes have not been changed



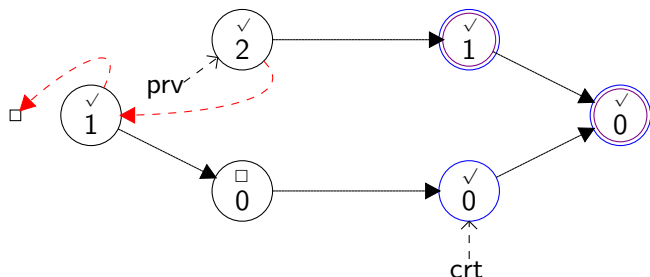
```
\forall HeapObject ho; (ho != null & ho.visited=FALSE ->
  (ho.nextChild = 0 &
    \forall int i; ((i>=0 & i<ho.children.length) ->
      ho.children[i]=childrenPre(ho,i))))
```

Loop Inv. – Visited nodes (*not* on the backtracking path)



```
\forall HeapObject h; ((h != null & h.visited = TRUE) ->
  (\forall int i; ((i >= 0 & i < h.nextChild - 1) ->
    (h.children[i].visited = TRUE &
     h.children[i] = childrenPre(h, i))))
  & ((!(\exists int dist; onPath[...](sw.previous, h, dist)))
    -> ( (h != sw.current -> h.nextChild = h.children.length) &
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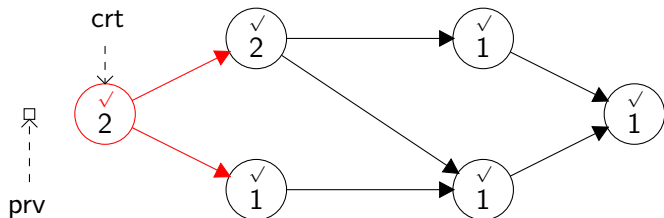

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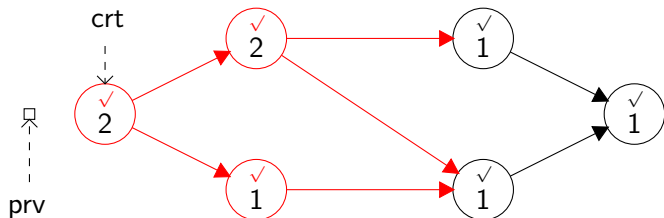
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Verification–Use Case



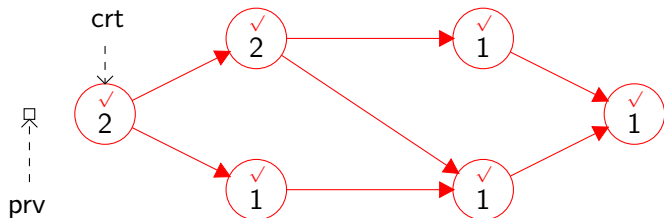
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Verification–Use Case

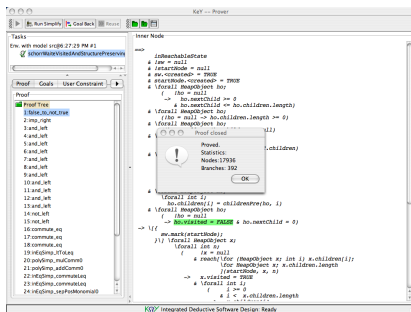


1. **Base Case:** use loop invariant conjunction est. the property for the start node (not shown)
2. **Step Case:** use loop invariant for visited nodes not on the backtracking path
3. **Use Case:** all nodes are visited and graph structure is unchanged

Verification–Statistics

Some statistics

proof steps	17936
interactive steps	1017
branches	392



Interactive steps have been required for

- ▶ quantifier instantiation
- ▶ *reachable* and *onPath* rule applications
- ▶ induction closing the use case

Conclusions

Verified Schorr-Waite algorithm implementation working on general graphs.

But too many user interactions required:

- ▶ possible to remove redundancies in loop invariant
- ▶ use KeY version with automatic quantifier treatment